

Amendments to the Claims:

This listing of claims will replace all prior versions, and listings of claims in the application:

1. (Currently Amended) Device for balancing of [[a]] radial threaded spindle eccentricity of a spindle drive (1) to avoid blocking of the spindle drive during lifting movement of a platform (2), ~~especially during lifting movement of the comprising: a platform with for lifting objects (S) in a machine, in which the said platform is being mounted by means of several bearing devices (L1; L2; L3; L4) respectively arranged on it on~~ several axiparallel spindles (G1; G2; G3; G4), ~~and can be lifted axially along the spindles together, with the bearing devices characterized by the spindle drive (1) having at least three axiparallel, rotatable threaded spindles (G1; G2; G3; G4) with said bearing devices (L1; L2; L3; L4) with different or the same having respective radial bearing clearances (F1; F2) in a polygonal arrangement; and low friction said bearing devices (L1; L2; L3; L4) being of a low-friction type, and arranged with radial bearing clearance (F1; F2) to balance the radial eccentricity of the rotating threaded spindle so that a relative radial movement of the rotating spindles to platform (2) with limited friction force is possible.~~

2. (Currently Amended) Device according to Claim 1, characterized by ~~wherein~~ a first bearing device (L1) of platform (2) arranged essentially radially on a first spindle (G1) free of play, a second bearing device (L2) having a radial bearing clearance (F1) on both sides of a second spindle (G2), which is prescribed to run radially and linearly back-and-forth from the first spindle (G1), and ~~the~~ a third and additional bearing device[[s]] (L3, L4) arranged with radial bearing clearance (F2) that is active all the way around the ~~corresponding~~ third and additional spindle[[s]] (G3,G4).

3. (Cancelled)

4. (Currently Amended) Device according to Claim 1 characterized by
~~the~~ wherein said bearing devices (L1; L2; L3; L4) each having an annular ball bearing (3) arranged concentrically around the spindle (G1; G2; G3; G4) by which the radial bearing clearance (F1; F2) between platform (2) and the spindle can be produced substantially free of friction to balance ~~the~~ threaded spindle eccentricity.

5. (Currently Amended) Device according to Claim 2, characterized by
wherein limitation of the radial bearing clearance (F1; F2) between bearing devices (L2; L3; L4) and respective spindles (G2; G3; G4) being produced by limitation devices (21; 22) arranged on platform (2) and engaging the spindles radially.

6. (Currently Amended) Device according to Claim [[3]] 2, characterized by wherein for limitation of the radial bearing clearance (F2) between the bearing devices (L1; L2; L3; L4) and the spindles (G1; G2; G3; G4) and to avoid radial movement of the platform (2), fixed limitation devices (50), ~~being~~ arranged on the apparatus side, ~~which~~ said fixed limitation devices (50) engage at right angles to the lifting movement on all four sides of platform (2).

7. (Currently Amended) Device for balancing of [[a]] radial ~~threaded~~ spindle eccentricity of a spindle drive (1) in order to avoid blocking of the spindle drive during lifting of a platform (2), ~~especially during lifting movement of the~~ comprising: a platform ~~with~~ for lifting objects (S) in a machine, ~~in which the~~ said platform is being mounted by ~~means of~~ several bearing devices (L1; L2; L3; L4) respectively arranged on ~~it~~ on several axiparallel spindles (G1; G2; G3; G4), ~~and can be~~ lifted together with the bearing devices axially along the spindles, characterized by ~~the~~ said bearing devices (L1; L2; L3; L4) each having an annular ball bearing (3) arranged concentrically around the spindles (G1; G2; G3; G4) by which a radial bearing clearance (F1; F2) can be produced between said platform (2) and the spindles to balance the threaded spindle eccentricity in low-friction fashion.

8. (Currently Amended) Device according to Claim 7, characterized by the wherein said ball bearings (3) each having a first plane bearing shell (31) aligned at right angles to the lifting movement and a second plane bearing shell (32) aligned plane-parallel to the said first plane, between which, held by an annular cage (33; 33.1; 33.2), the balls (34) of each ball bearing are held by an annular cage (33; 33.1; 33.2) and mounted to rotate freely, the said first plane bearing shell (31) of the ball bearing (3) being rigidly connected to a corresponding spindle (M1; M2; M3; M4), of the bearing device (L1; L2; L3; L4) and the said second plane bearing shell (32) being rigidly connected to the said platform (2).

9. (Currently Amended) Device according to Claim 8, characterized by the wherein said plane bearing shells (31;32) having a plane support width in the radial direction for the said balls (34) in the radial direction, which width is greater than the maximum radial bearing clearance (F1; F2) predetermined by the maximum spindle eccentricity, and the said ball cage (33; 33.1; 33.2) having an outer (33.1) and an inner (33.2) annular element around the said balls (34), in a concentric arrangement around said spindles (G1; G2; G3; G4), the inner annular element (33.2) having an inside diameter that essentially corresponds to an outside diameter of the said spindle (M1; M2; M3; M4).

10. (Currently Amended) Device according to Claim 7, characterized by the wherein said bearing devices (L1; L2; L3; L4) each having have an annular ball bearing (4) arranged concentrically around a respective threaded spindle (G1; G2; G3; G4), a first concave, ball-guiding bearing shell (41) of the said annular ball bearing being rigidly connected to a spindle (M1; M2; M3; M4), of the bearing device (L1; L2; L3; L4) and whose a second bearing shell (42) is rigidly connected to said platform (2) in a plane-parallel position relative to the said first bearing shell (41), and has a plane support side for the said balls (44) of said ball bearing (4).

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A2

11. **(Currently Amended)** Device according to Claim 10, characterized by wherein all threaded spindles (G1; G2; G3; G4) of the spindle drive (1) ~~being~~ are driven synchronously by a single microprocessor-controlled drive unit (6); and the spindle drive (1) ~~with its~~ said platform (2) ~~having~~ has a vertically directed lifting movement.

12. **(Cancelled)**

13. **(Currently Amended)** Device according to Claim 11, characterized by ~~the~~ wherein said spindles (G1; G2; G3; G4) ~~having~~ have a combination of threaded spindles and cylinder shafts, the said cylinder shafts being used for guiding, and as rotational and tilting protection for, said platform (2).